

Leveraging Prior Knowledge for Effective Design-Space Exploration in High-Level Synthesis

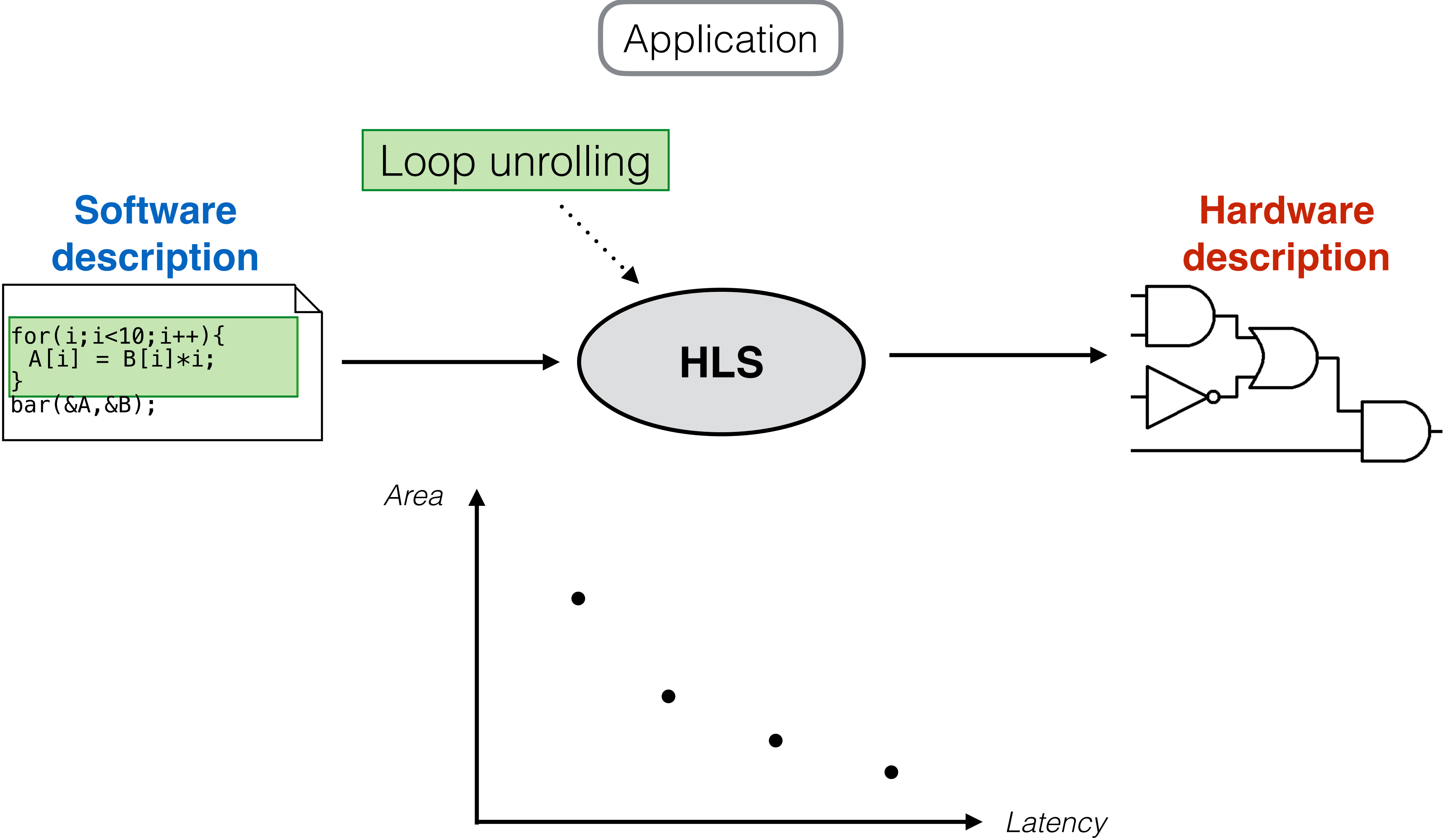
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Giuseppe Di Guglielmo², Luca Carloni², Laura Pozzi¹,

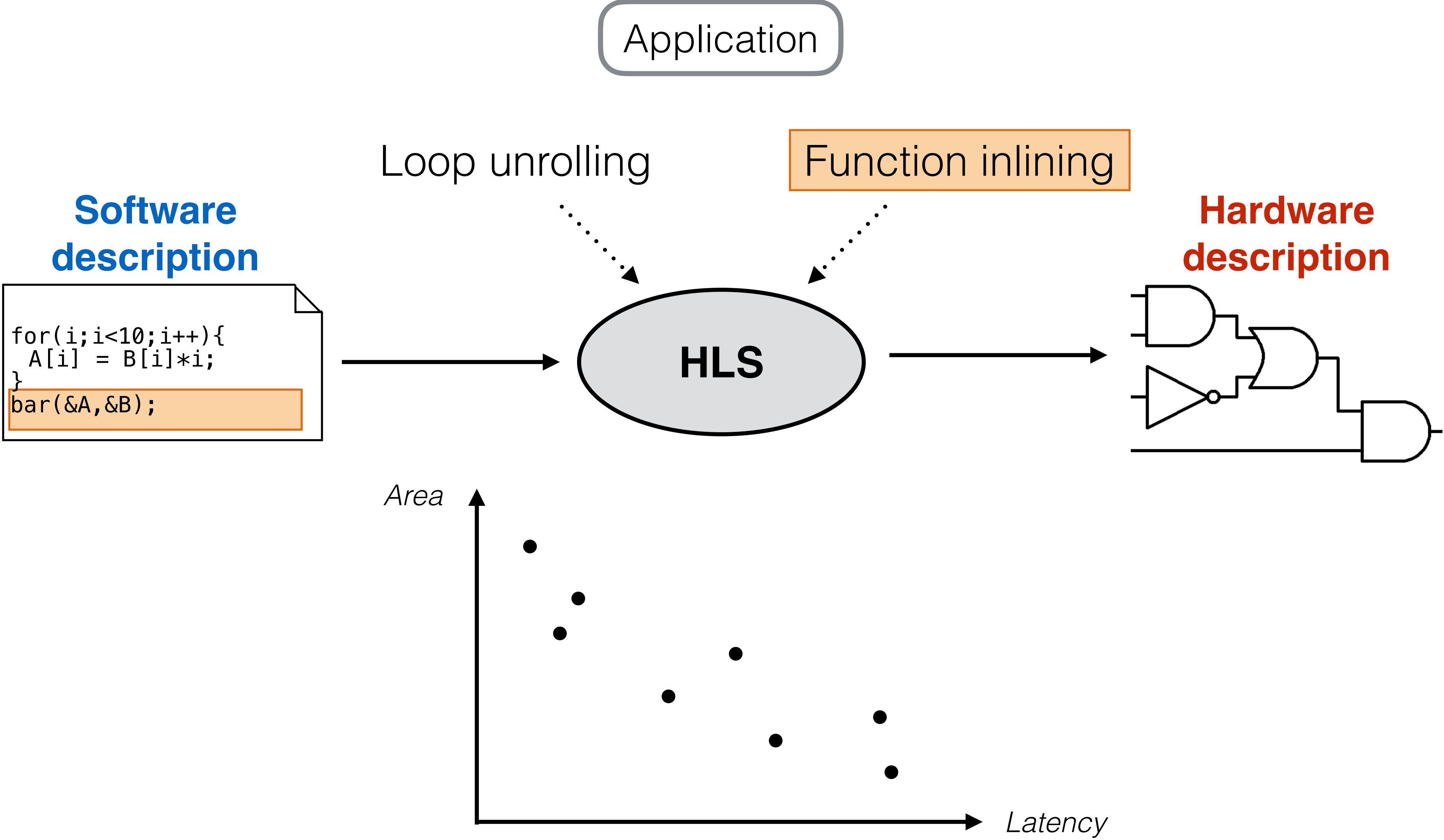
¹ Università della Svizzera italiana, Lugano, Switzerland

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Motivation



Motivation



Motivation

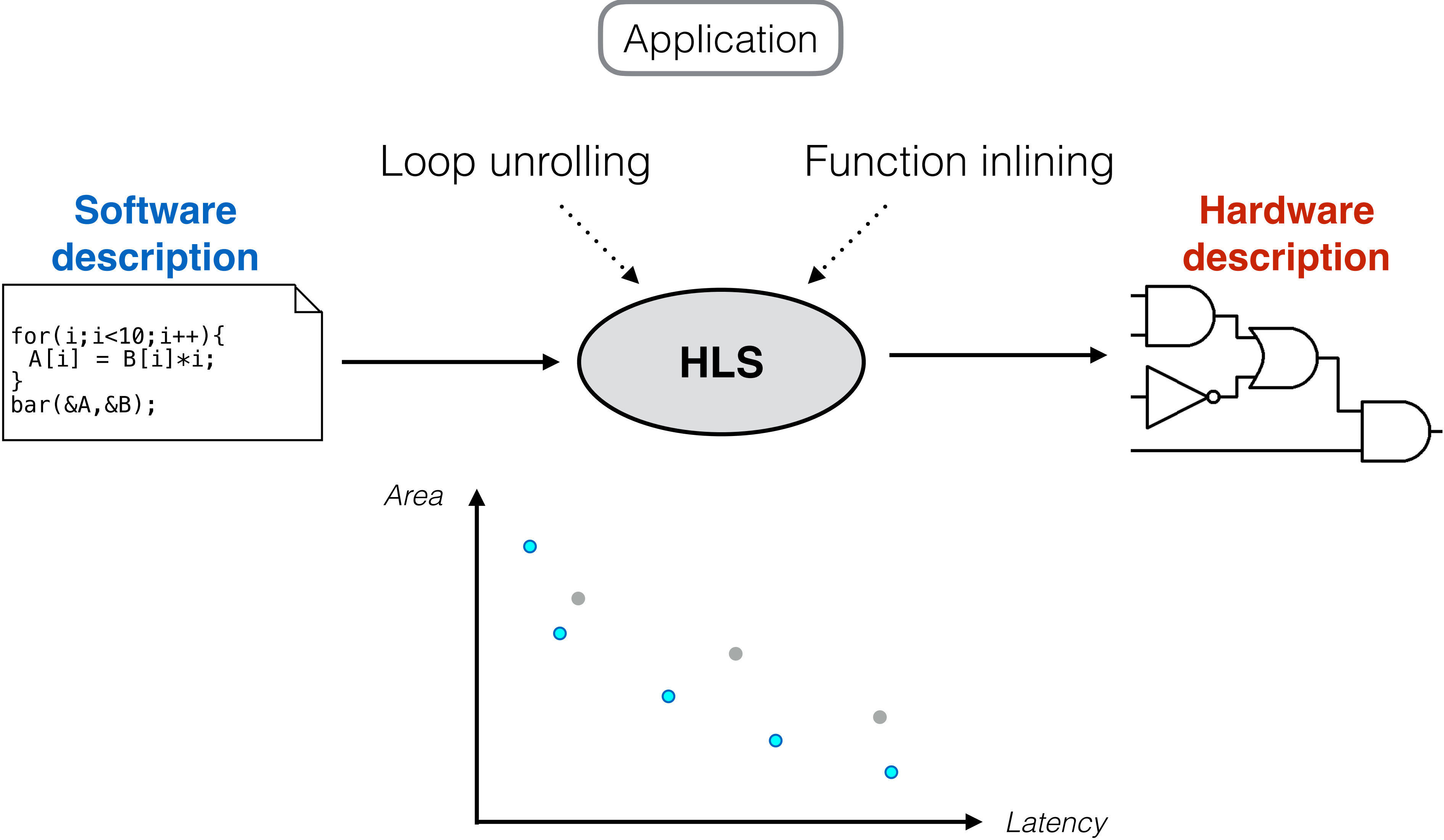
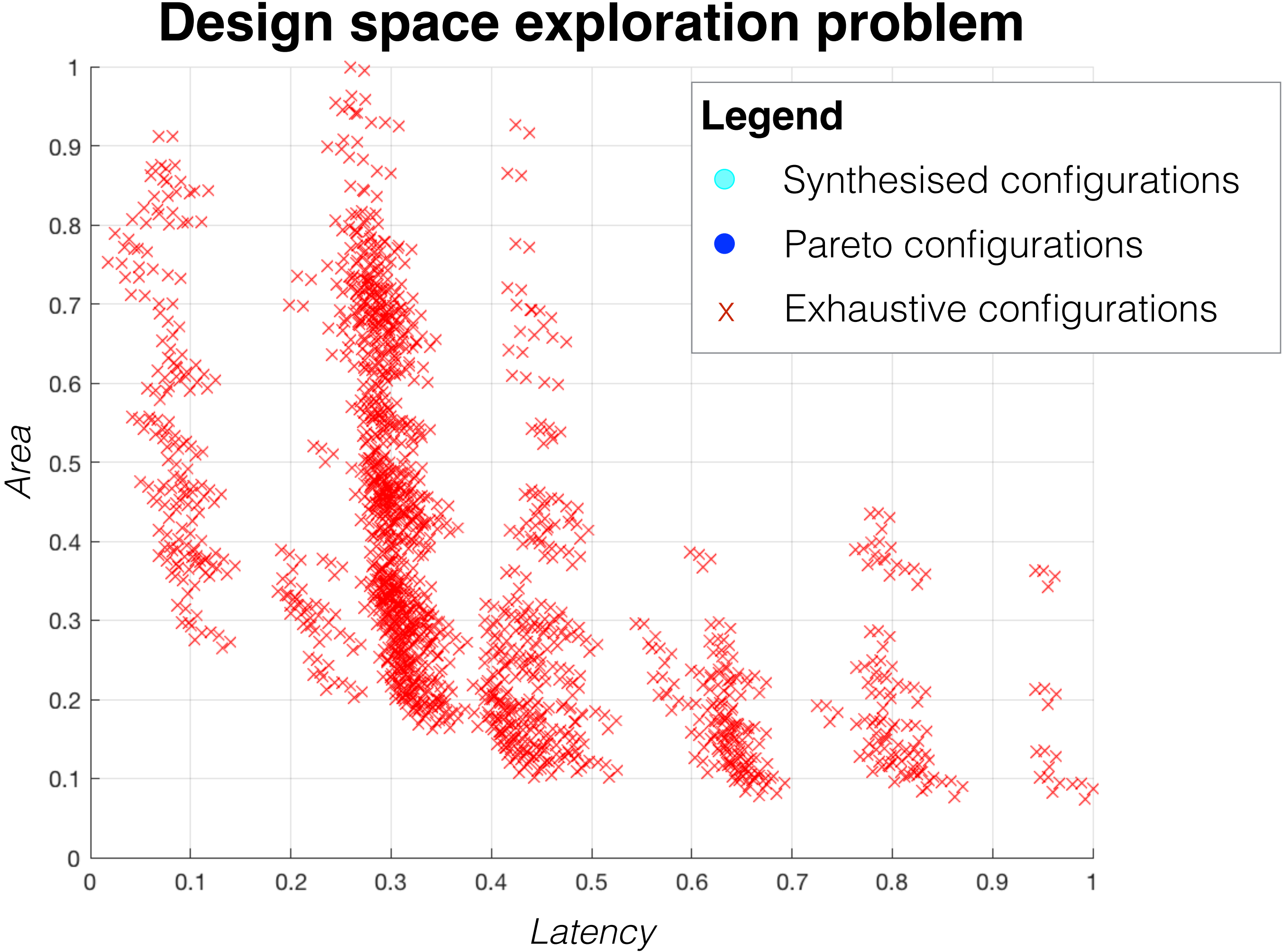


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 - State of the Art
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 - The Methodology
 - Signature Encoding
 - Similarity Evaluation
 - Inference Process
 - Results

HLS-driven Design Space Exploration (DSE)

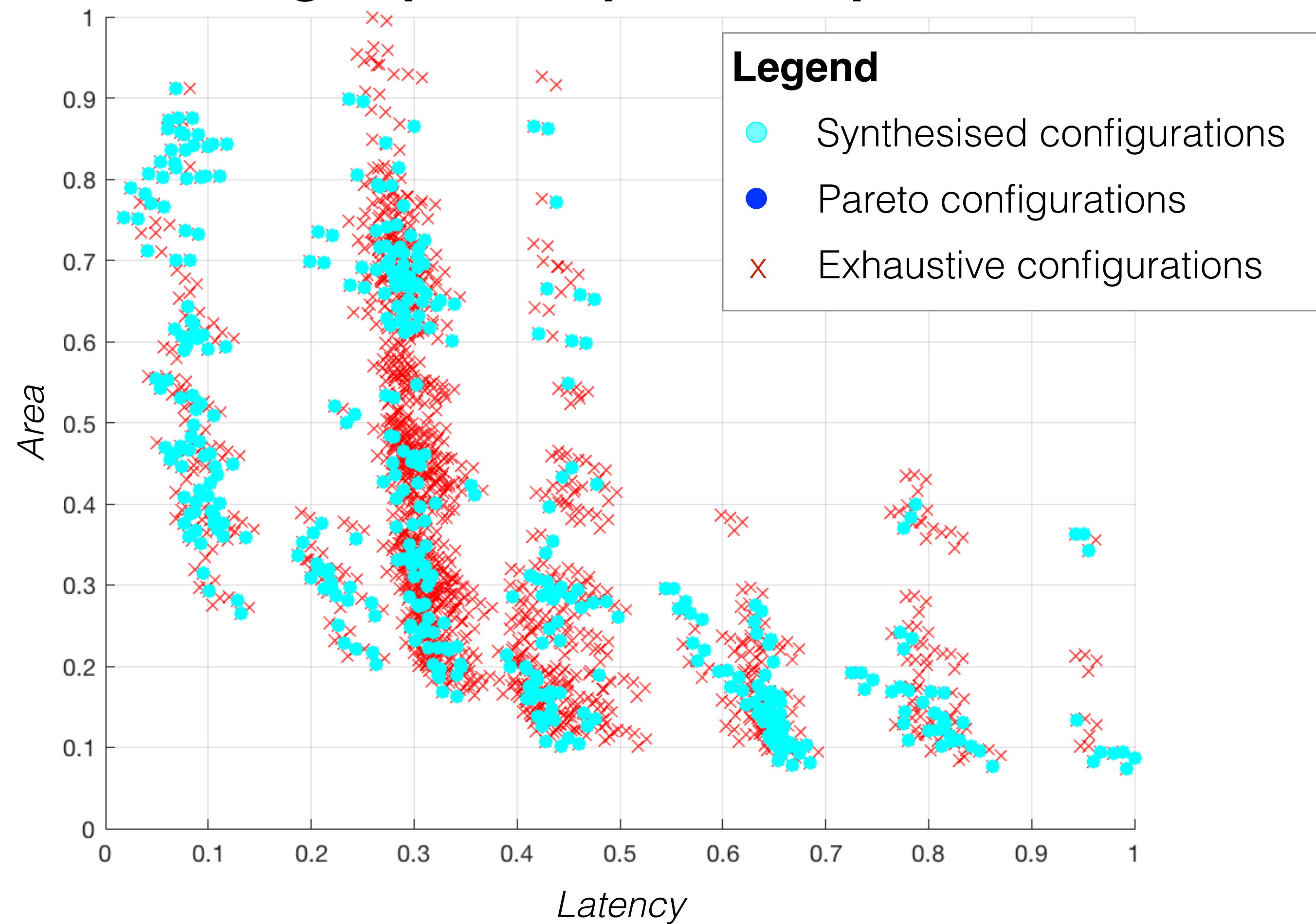
Goal: get close to the Pareto solutions while minimising the number of synthesis.



HLS-driven Design Space Exploration (DSE)

Goal: get close to the Pareto solutions while minimising the number of synthesis.

Design space exploration problem



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Design space exploration problem

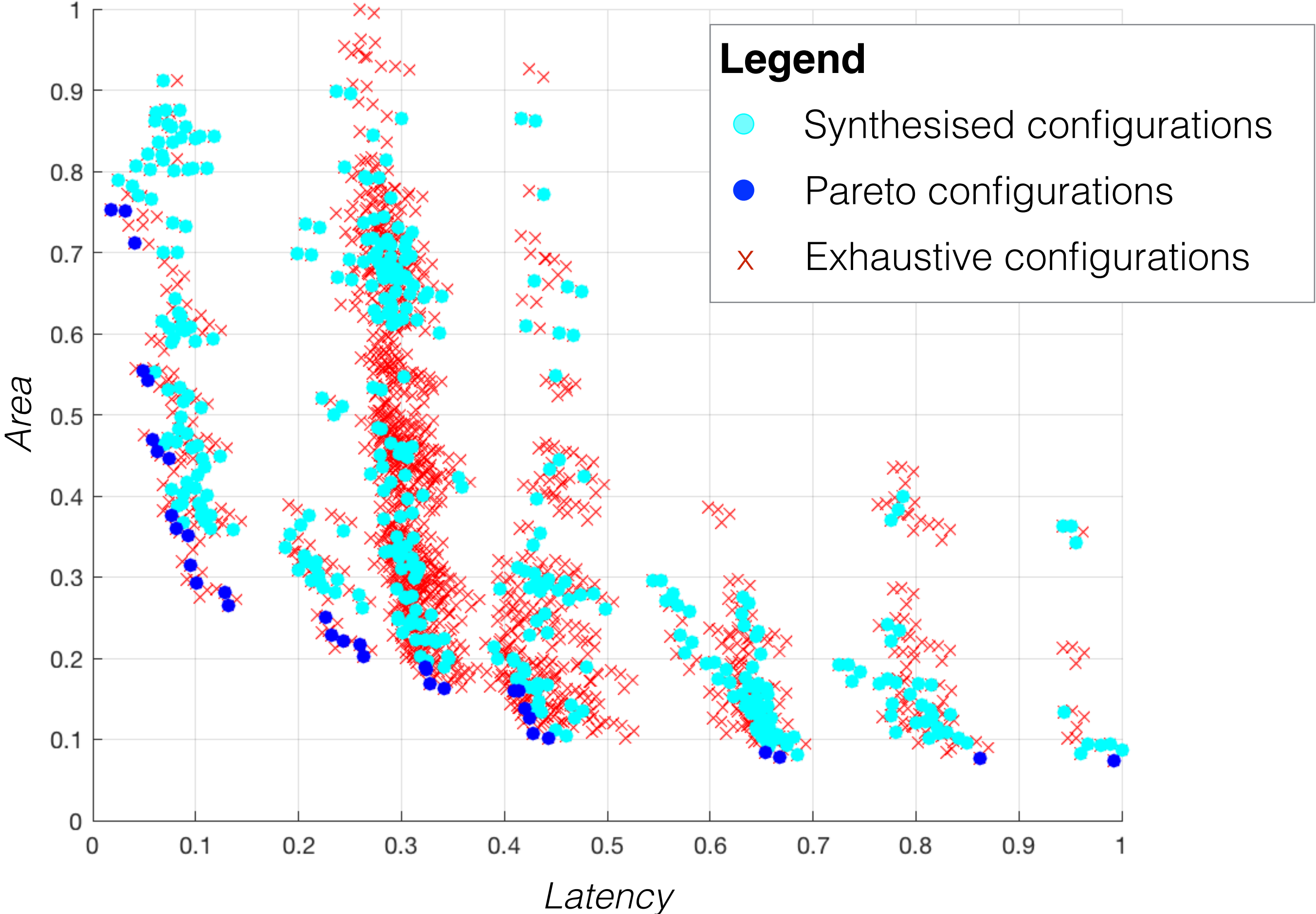


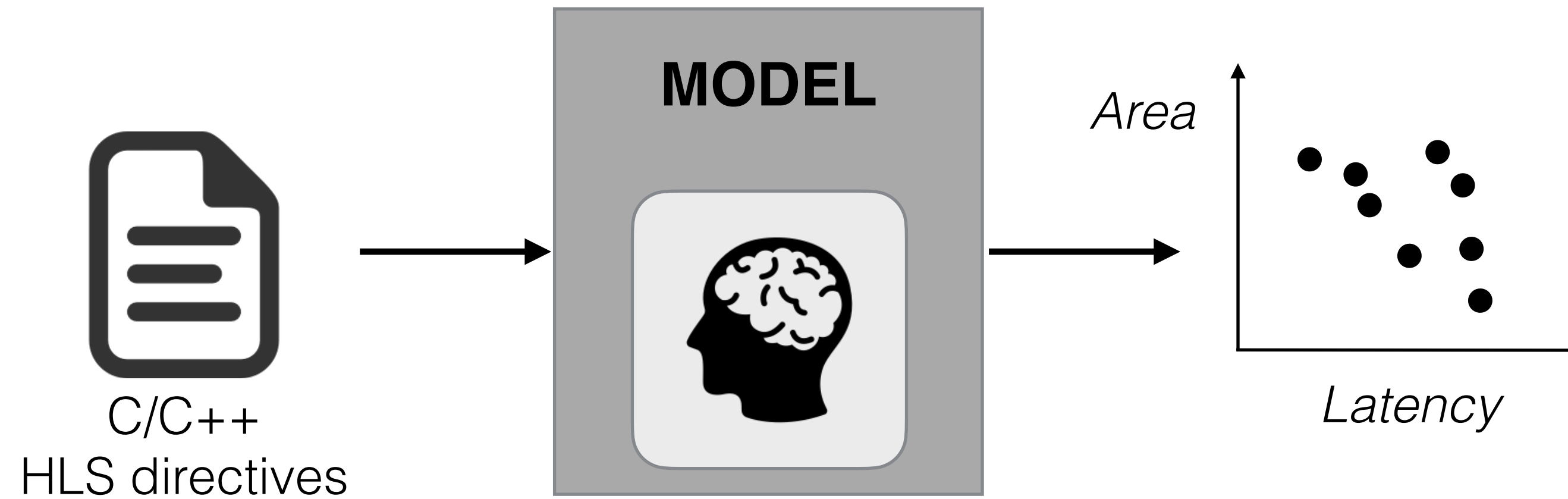
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State of the Art for DSE

Two main approaches:

- Model-based methodologies

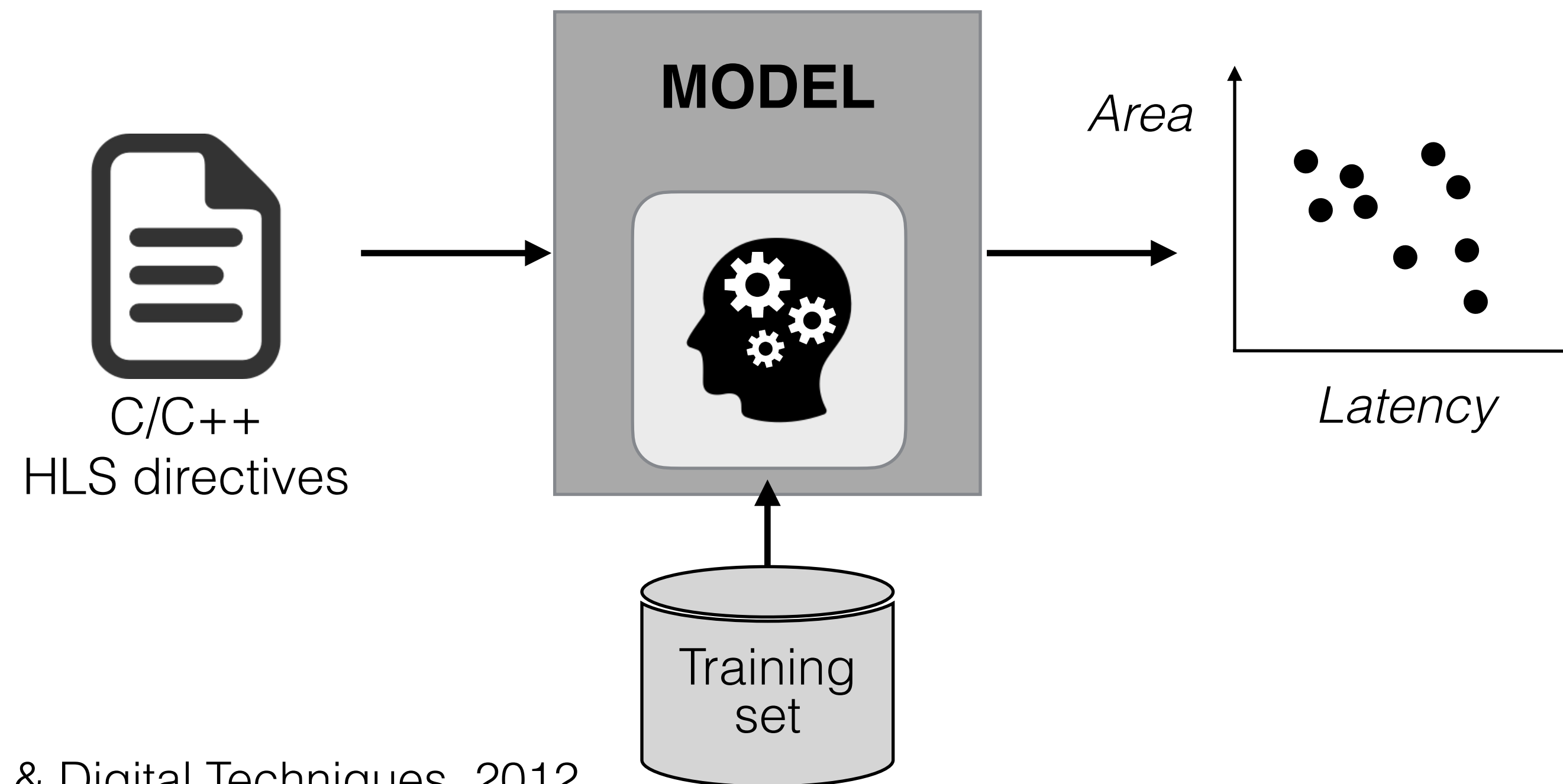


- [11] Zhong et al. International Conference on Computer Design, 2014.
[12] N. K. Pham et al. Design, Automation Test in Europe Conference Exhibition, 2015.
[13] Zhong et al. International Conference on Computer Design, 2016.
[14] J. Zhao et al. International Conference on Computer Aided Design, 2017.

State of the Art for DSE

Two main approaches:

- Model-based methodologies
- Black-box-based methodologies
 - Training-based



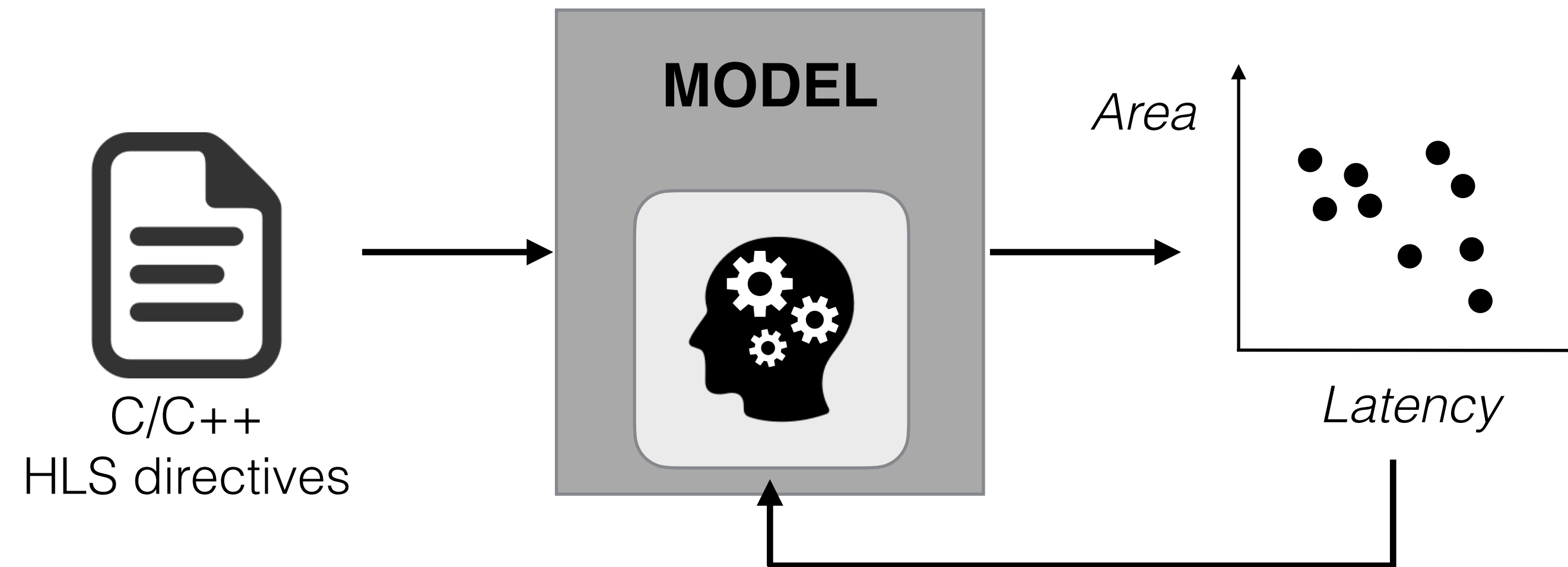
[15] Schafer et al. IET Computers & Digital Techniques, 2012.

[16] A. Mahapatra et al, Electronic System Level Synthesis Conference, 2014

State of the Art for DSE

Two main approaches:

- Model-based methodologies
- Black-box-based methodologies
 - Training-based
 - Refinement-based

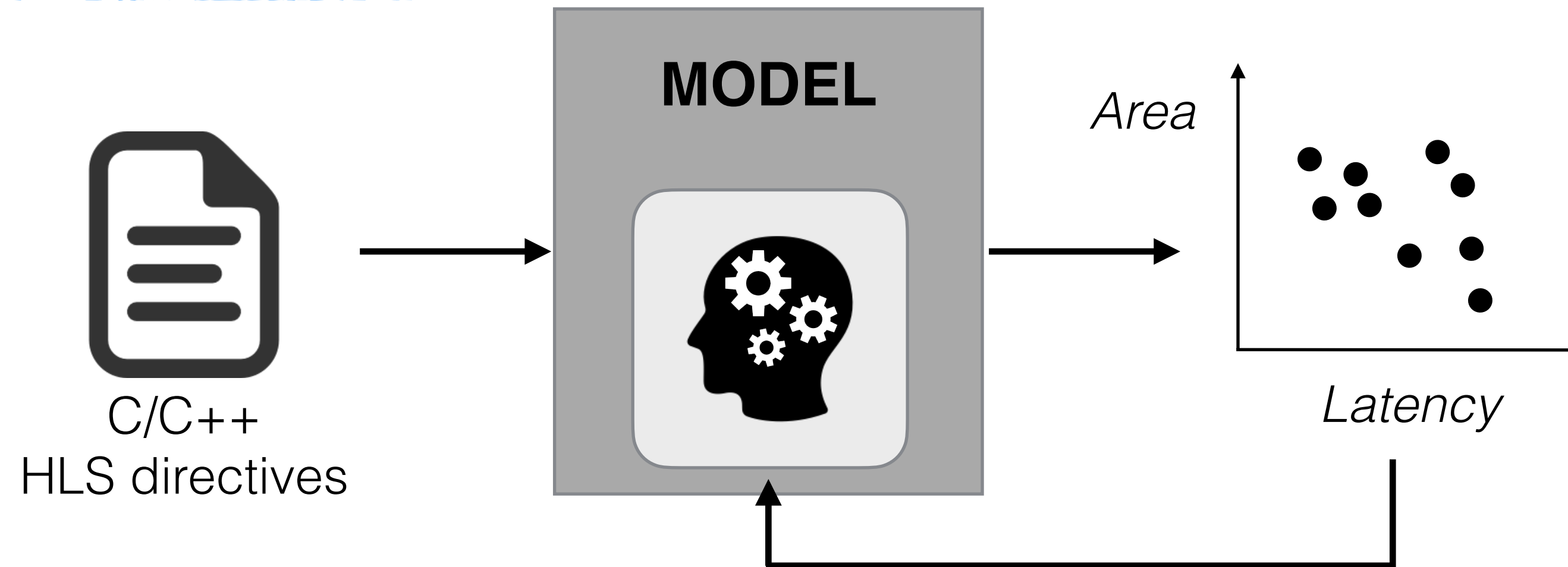


- [8] H. Liu et al. Design Automation Conference, 2013.
- [9] L. Ferretti et al. IEEE Transactions on Emerging Topics in Computing, 2018.
- [10] L. Ferretti et al. International Conference on Computer Design, 2018.
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State of the Art for DSE

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- Model-based methodologies
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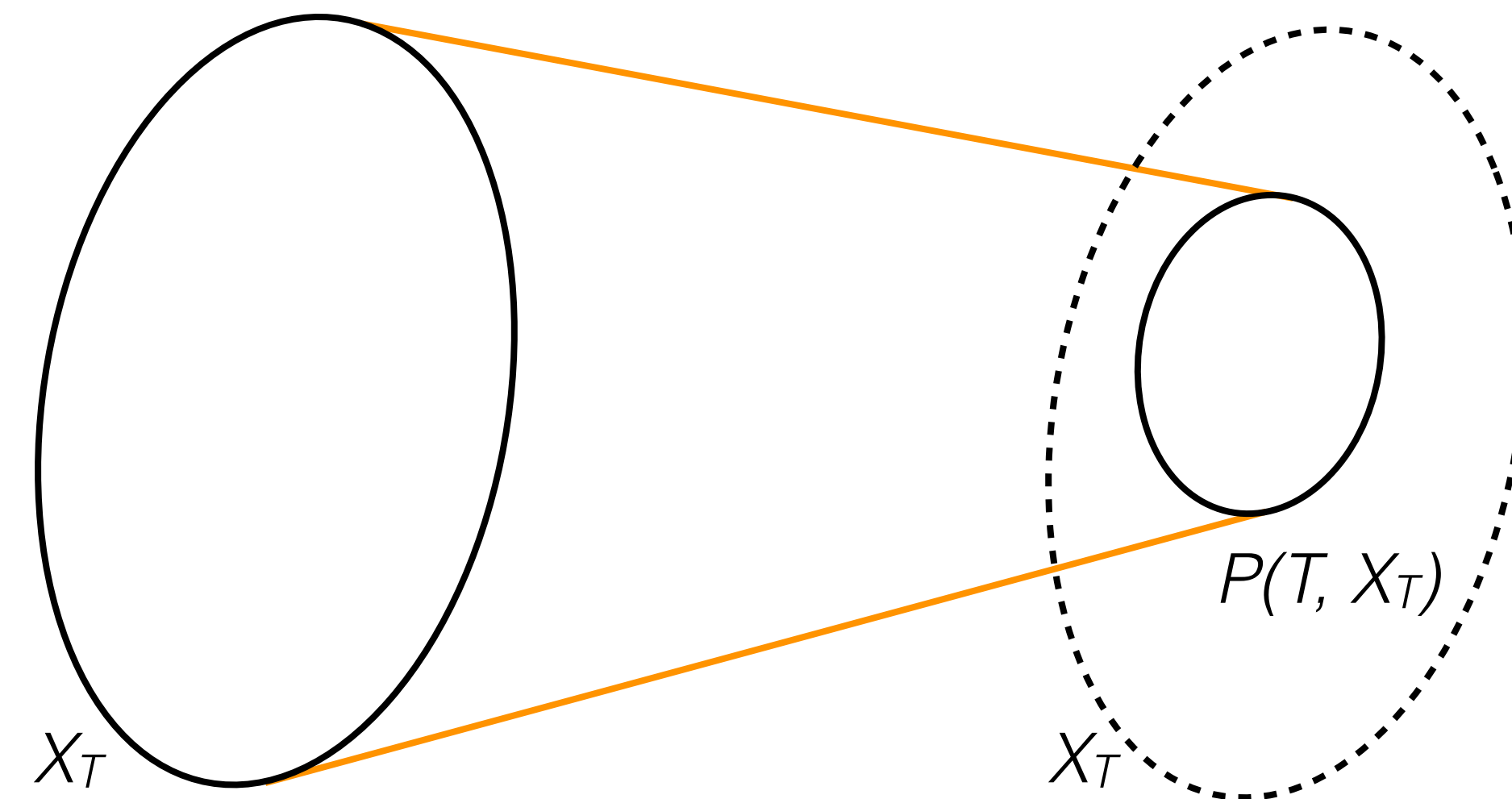
- [8] H. Liu et al. Design Automation Conference, 2013.
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The Idea: Leveraging Prior Knowledge

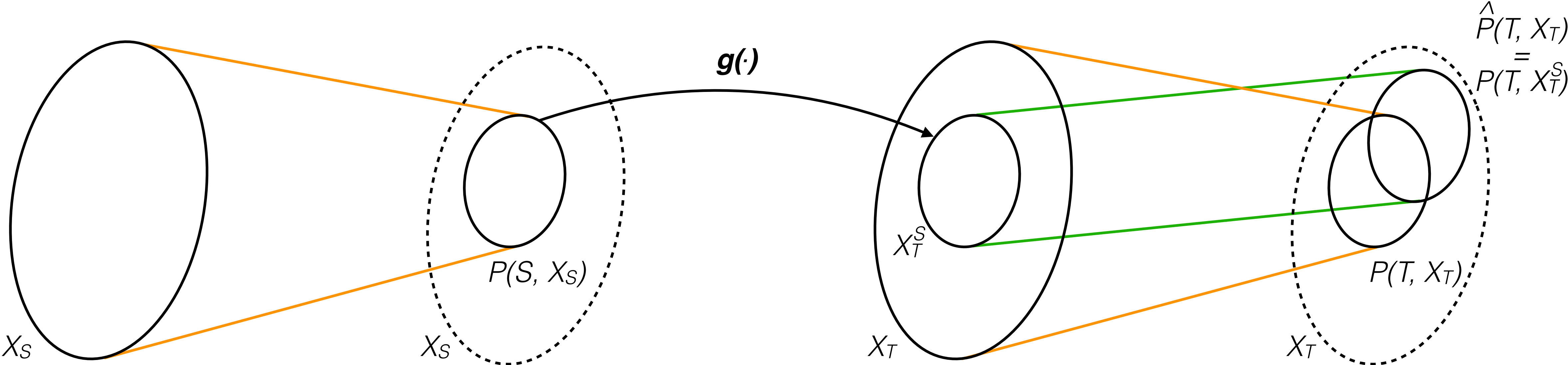
Standard approach



X_T Set of configurations explored in the DSE of a design T.
 $P(T, X_T)$ Set of Pareto-optimal configurations identified with the DSE of T.

The Idea: Leveraging Prior Knowledge

Leveraging Prior Knowledge approach



X_S Set of configurations explored in the DSE of a design S.
 $P(S, X_S)$ Set of Pareto-optimal configurations identified with the DSE of S.

X_T Set of configurations explored in the DSE of a design T.
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The Methodology

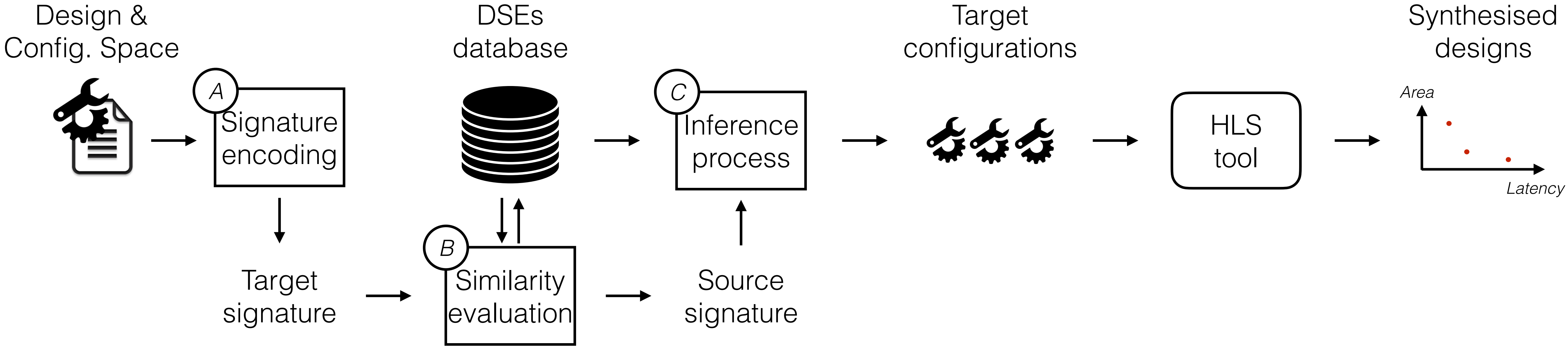


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The Methodology: Signature Encoding

A DSE is characterized with a simplified compact representation that abstracts the specification (code) and the associated configurations (set of applied directives).

Signature encoding : **Specification Encoding** & **Configuration Space Descriptor**

The **Specification Encoding (SE)** is a simplified representation of the original code describing those aspects of an HLS-application that can be targeted by HLS directives.

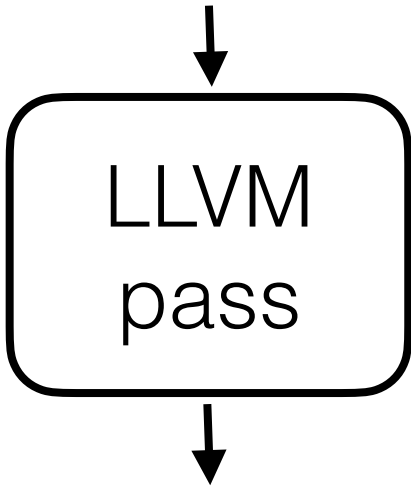
The **Configuration Space Descriptor (CSD)** describes the user-defined configuration space indicating the set of optimisations type and values considered for the DSE.

The Methodology: Signature Encoding

Specification Encoding (SE): simplified representation of the original code automatically generated through a compiler pass with LLVM.

- Specification Encoding symbols:
- Functions —> **F**
 - Function parameter passed by value —> **V**
 - Function parameter passed by reference —> **P**
 - Arrays definition or declaration —> **A**
 - Structs definition or declaration —> **S**
 - Loops —> **L**
 - Load operations (e.g. a = Array[0]) —> **R**
 - Store operations (e.g. Array[0] = a) —> **W**
 - Function call —> **C#<function_name>#**
 - Scope —> **{ }**

```
void last_step_scan(int bucket[BUCKETSIZE], int sum[SCAN_RADIX]) {  
    int radixID, i, bucket_indx;  
    last_1:for (radixID=0; radixID<SCAN_RADIX; radixID++) {  
        last_2:for (i=0; i<SCAN_BLOCK; i++) {  
            bucket_indx = radixID * SCAN_BLOCK + i;  
            bucket[bucket_indx] = bucket[bucket_indx] + sum[radixID];  
        }  
    }  
}
```



F{PP}L{L{RRW}}

Running Example

The Methodology: Signature Encoding

Configuration Space Descriptor (CSD): a DSL is created to describe the optimisations type and values considered for the DSE. A CSD defines entirely the user-defined configuration space.

Example of CSD:

```
resource;last_step_scan;bucket;{RAM_2P_BRAM}
resource;last_step_scan;sum;{RAM_2P_BRAM}
array_partition;last_step_scan;bucket;1;
  {cyclic,block};{1->512,pow_2}
array_partition;last_step_scan;sum;1;
  {cyclic,block};{1->128,pow_2}
unroll;last_step_scan;last_1;{1->128,pow_2}
unroll last_step_scan;last_2 {1,2,4,8,16}
clock;{10}
```

```
void last_step_scan(int bucket[BUCKETSIZE], int sum[SCAN_RADIX]) {
  int radixID, i, bucket_indx;
  last_1:for (radixID=0; radixID<SCAN_RADIX; radixID++) {
    last_2:for (i=0; i<SCAN_BLOCK; i++) {
      bucket_indx = radixID * SCAN_BLOCK + i;
      bucket[bucket_indx] = bucket[bucket_indx] + sum[radixID];
    }
  }
}
```

Directive type

Location

Set of directive values

Knob

Running Example

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The Methodology: Similarity Evaluation

Similarity Evaluation: in order to identify the proper source for the inference process the similarity among a target DSE and the available source is calculated.

The similarity function (Sim) is given by a linear combination of Signature Encoding similarity (Sim_{SE}) and Configuration Space Descriptor similarity (Sim_{CSD}).

$$Sim = \alpha Sim_{SE} + (1 - \alpha) Sim_{CSD} \quad \alpha \in [0,1]$$

$$Sim_{SE} = LCS(SE_T, SE_S)$$

$$Sim_{CSD} = 1 - \left[\frac{1}{I} \sum_{i=1}^I \Delta(K_i, M_{T,S}(K_i)) / D_{MAX} \right]$$

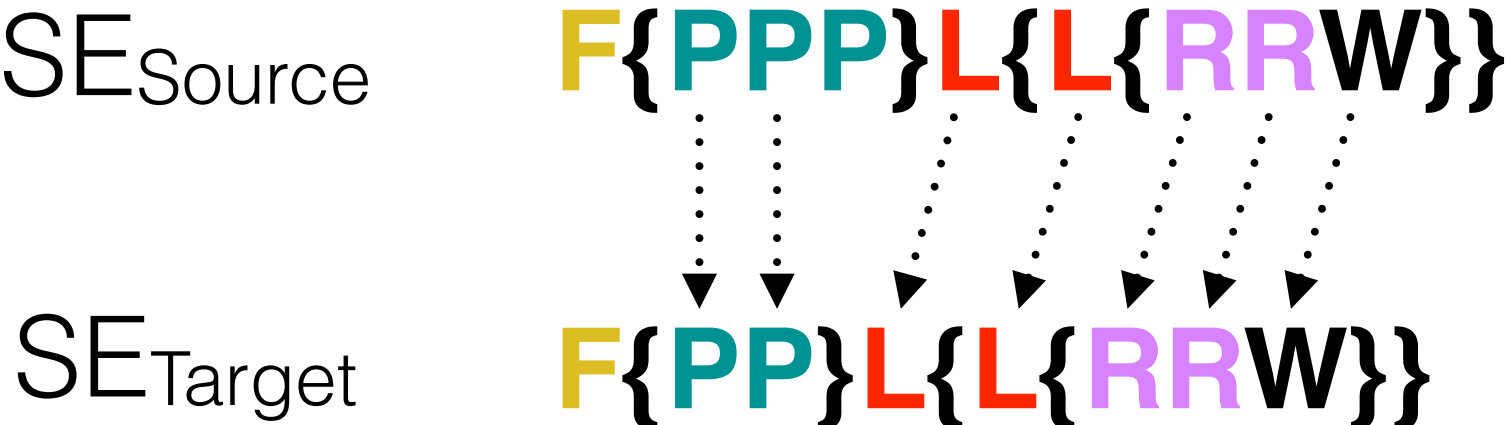
$$\Delta(K_i, K_j) = \sqrt{\sum_{n=1}^{|K_i|} \sum_{m=1}^{|K_j|} (\min | \delta(k_n, k_m) |)^2} \quad k_n \in K_i, k_m \in K_j$$

$$\delta(k_n, k_m) = \sqrt{\sum_{z=1}^Z |k_{n,z} - k_{m,z}|^2}$$

The Methodology: Similarity Evaluation

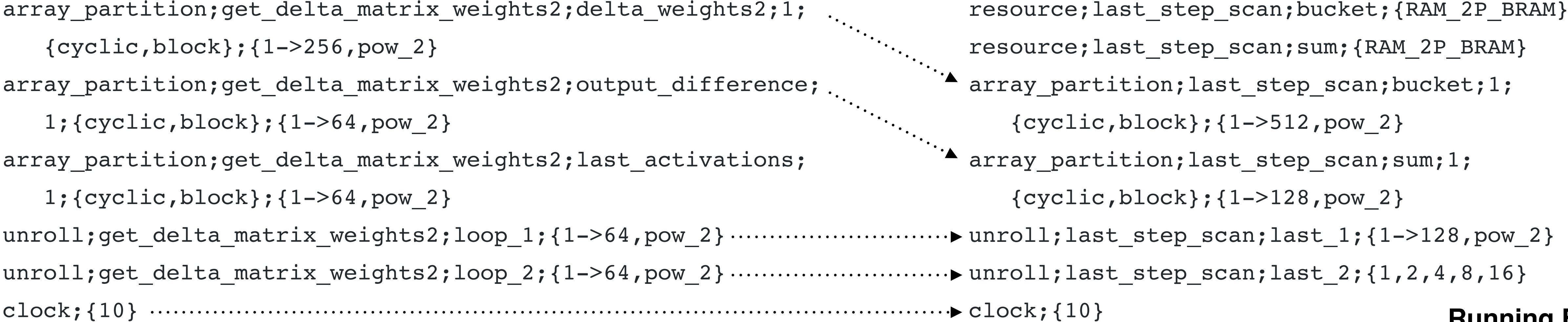
CSD similarity: measures the similarity among knobs of target and source CSDs.

A top-down mapping maps knobs of the source Signature Encoding to knobs of the target one.



CSD_{Source}

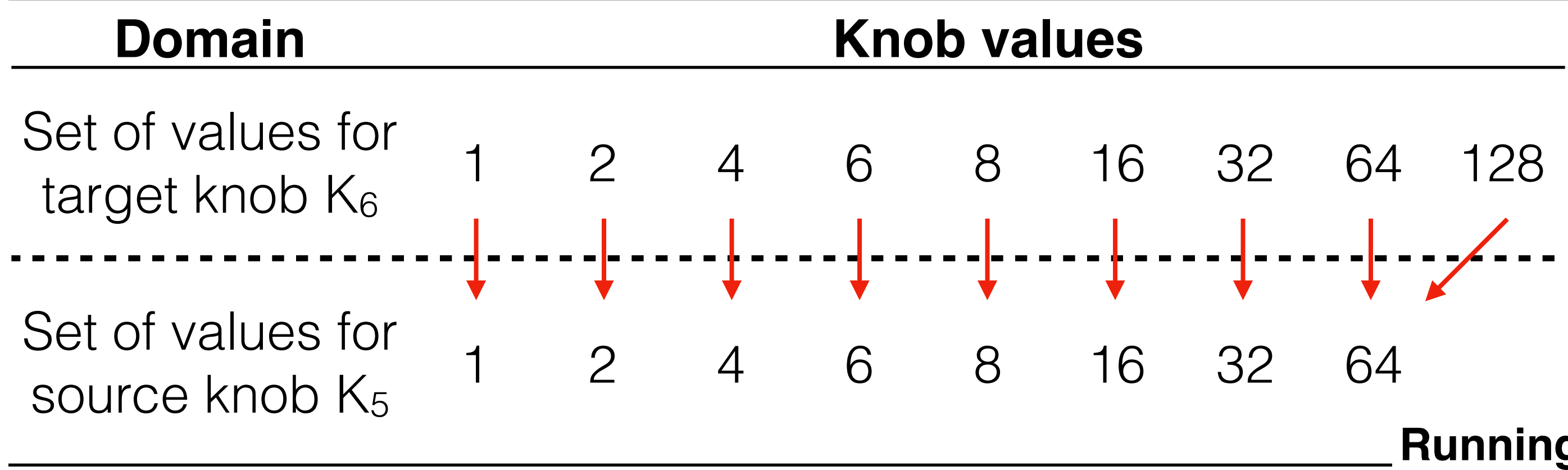
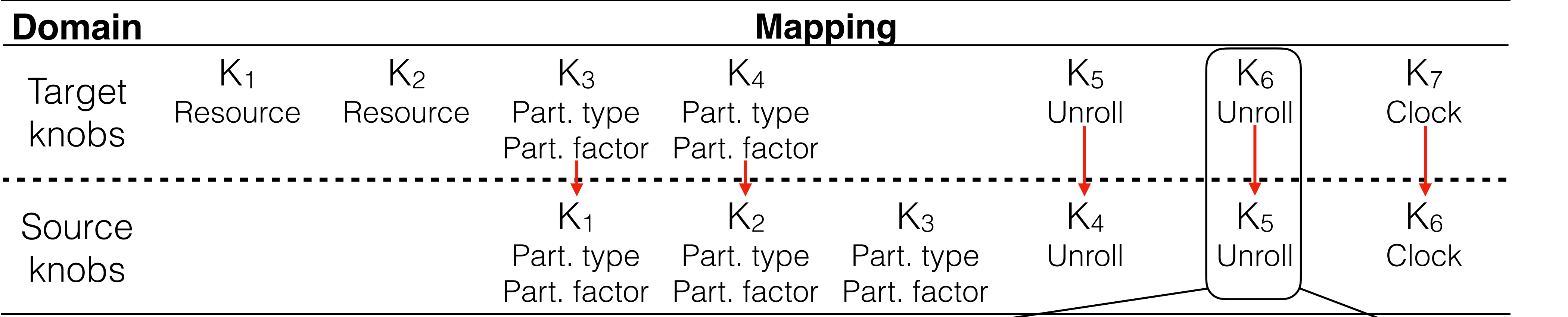
CSD_{Target}



Running Example

The Methodology: Similarity Evaluation

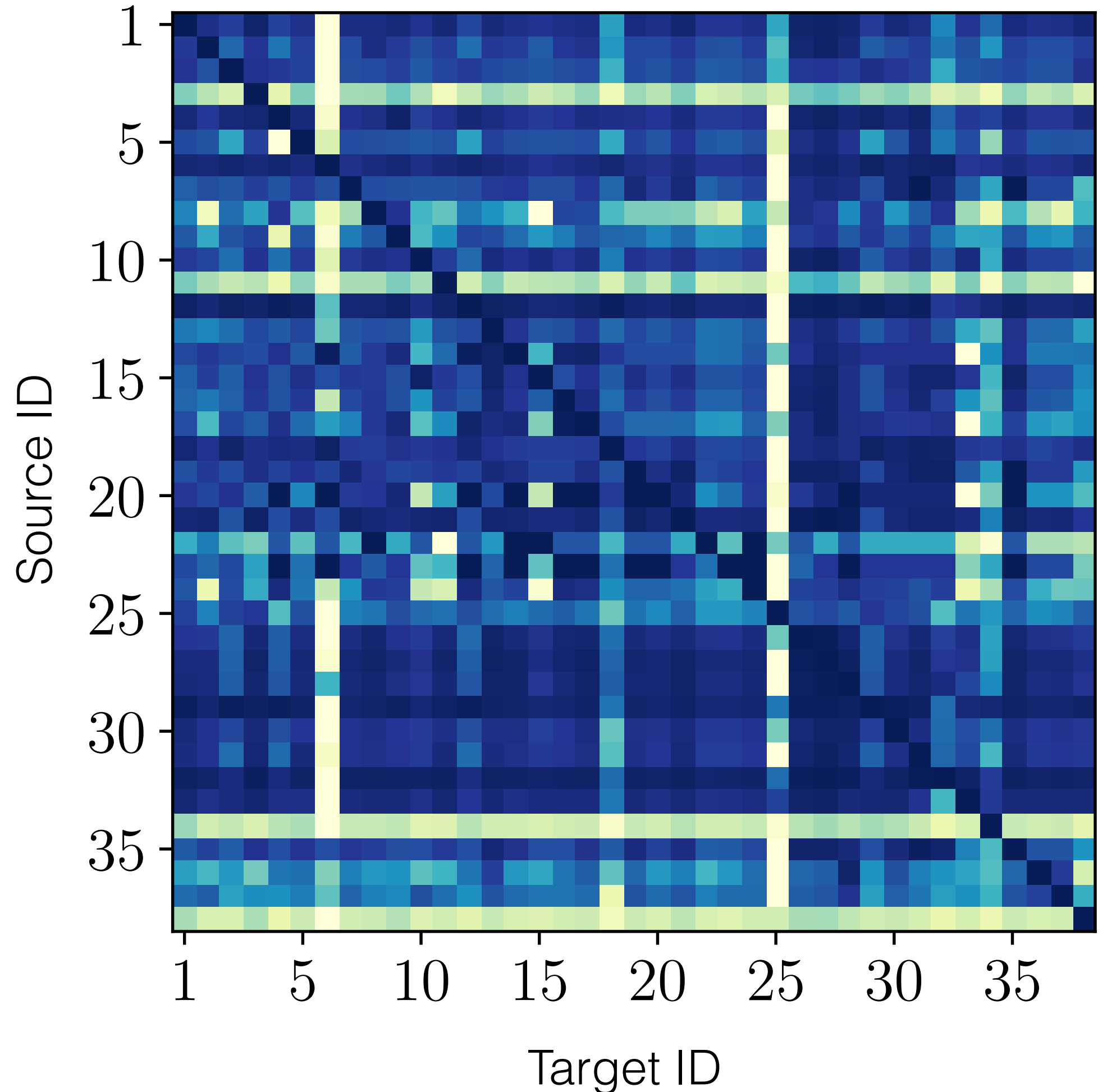
CSD similarity: measures the similarity among knobs of target and source CSDs.



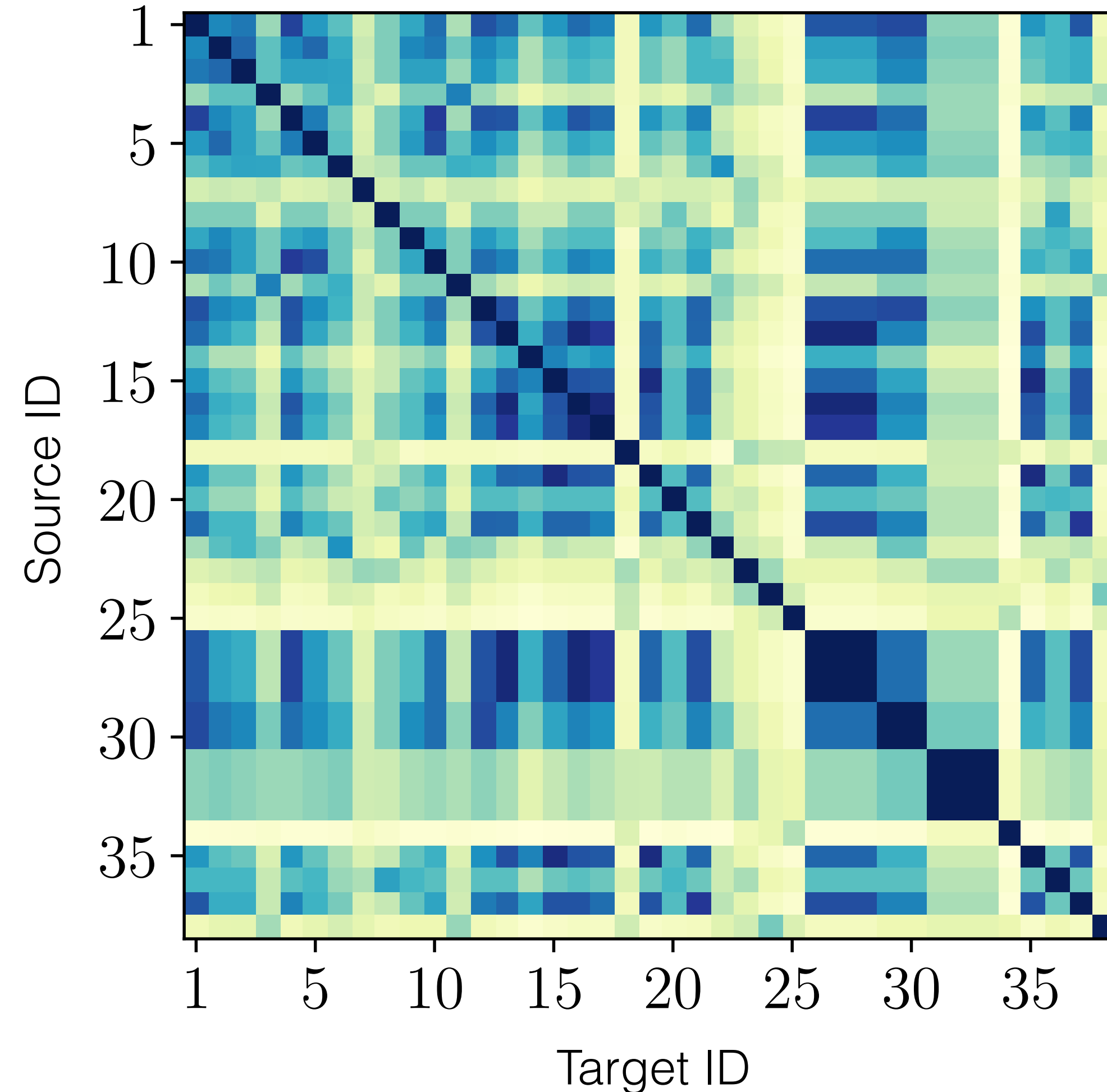
Running Example

The Methodology: Similarity Evaluation

Sim_{SE}



Sim_{CSD}



The Methodology: Similarity Evaluation

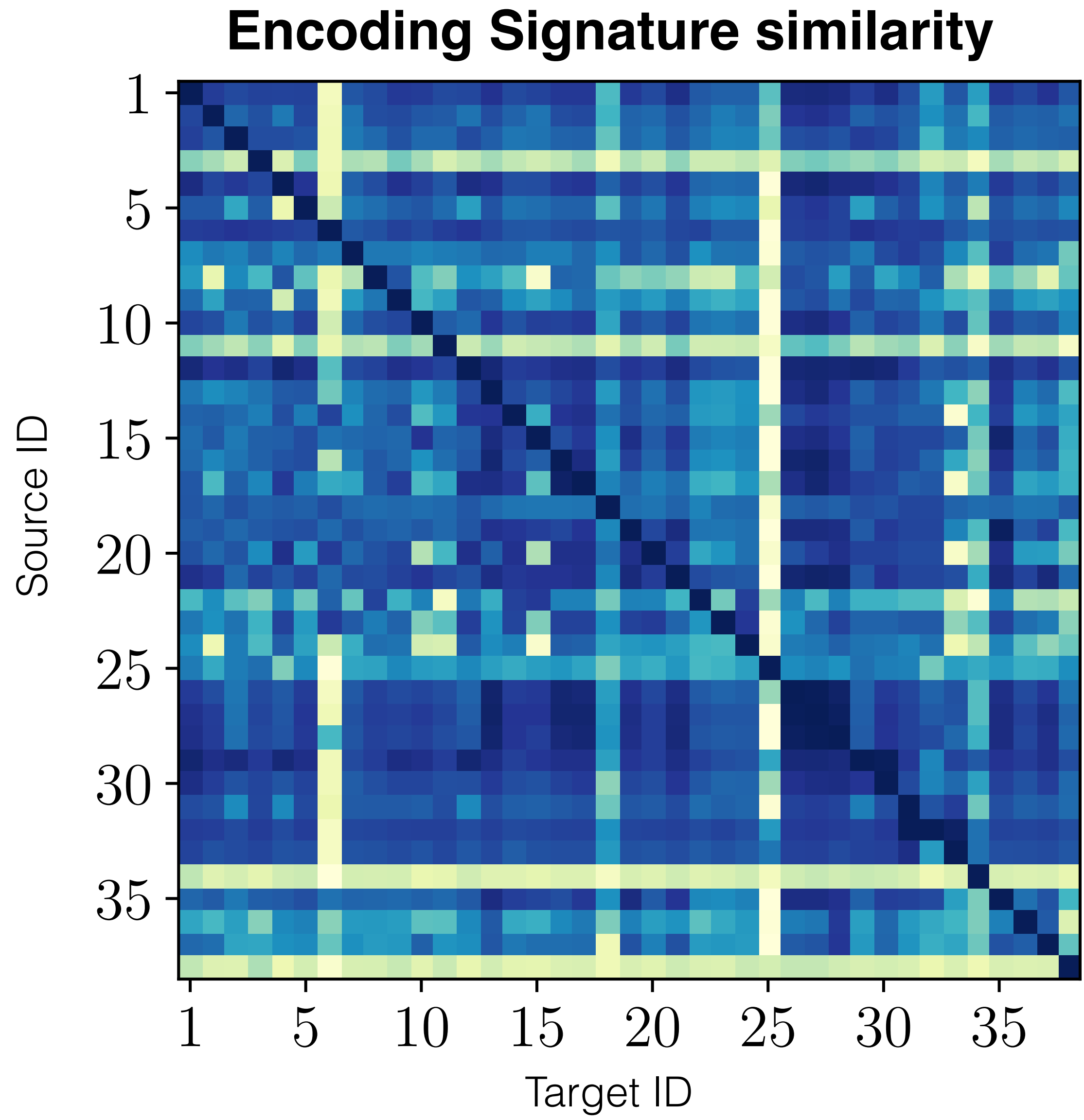
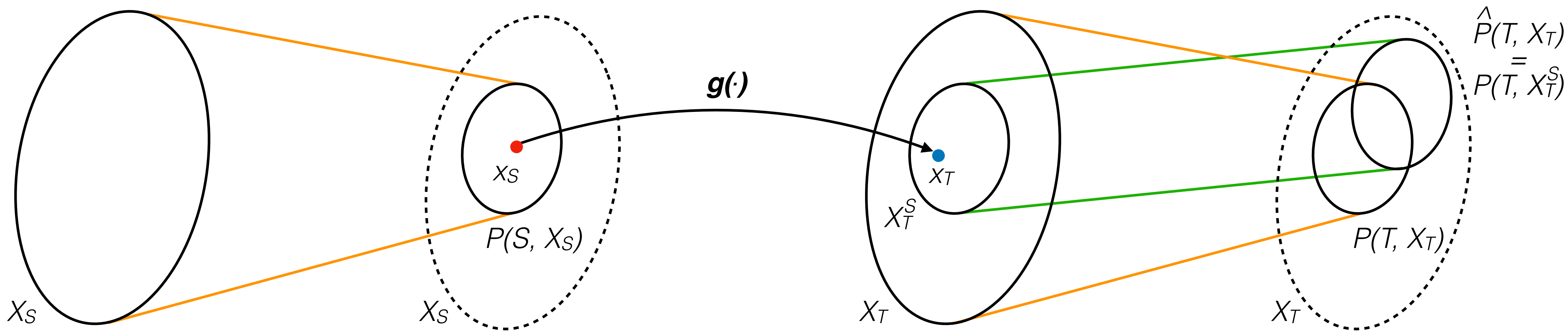


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The methodology: Inference Process



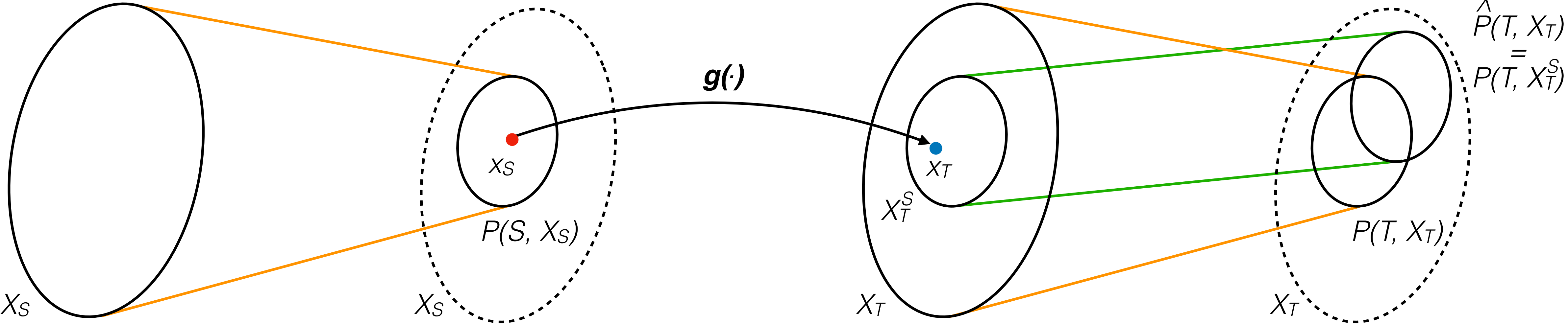
$$x_S = [x_S^1, \dots, x_S^J] \in X_S$$

$$x_T = [x_T^1, \dots, x_T^I] \in X_T$$

$$x_T^i = \underset{n}{\operatorname{argmin}} \{ \delta(k_n, x_S^j) \}$$

$$\delta(k_n, k_m) = \sqrt{\sum_{z=1}^Z |k_{n,z} - k_{m,z}|^2}$$

The methodology: Inference Process

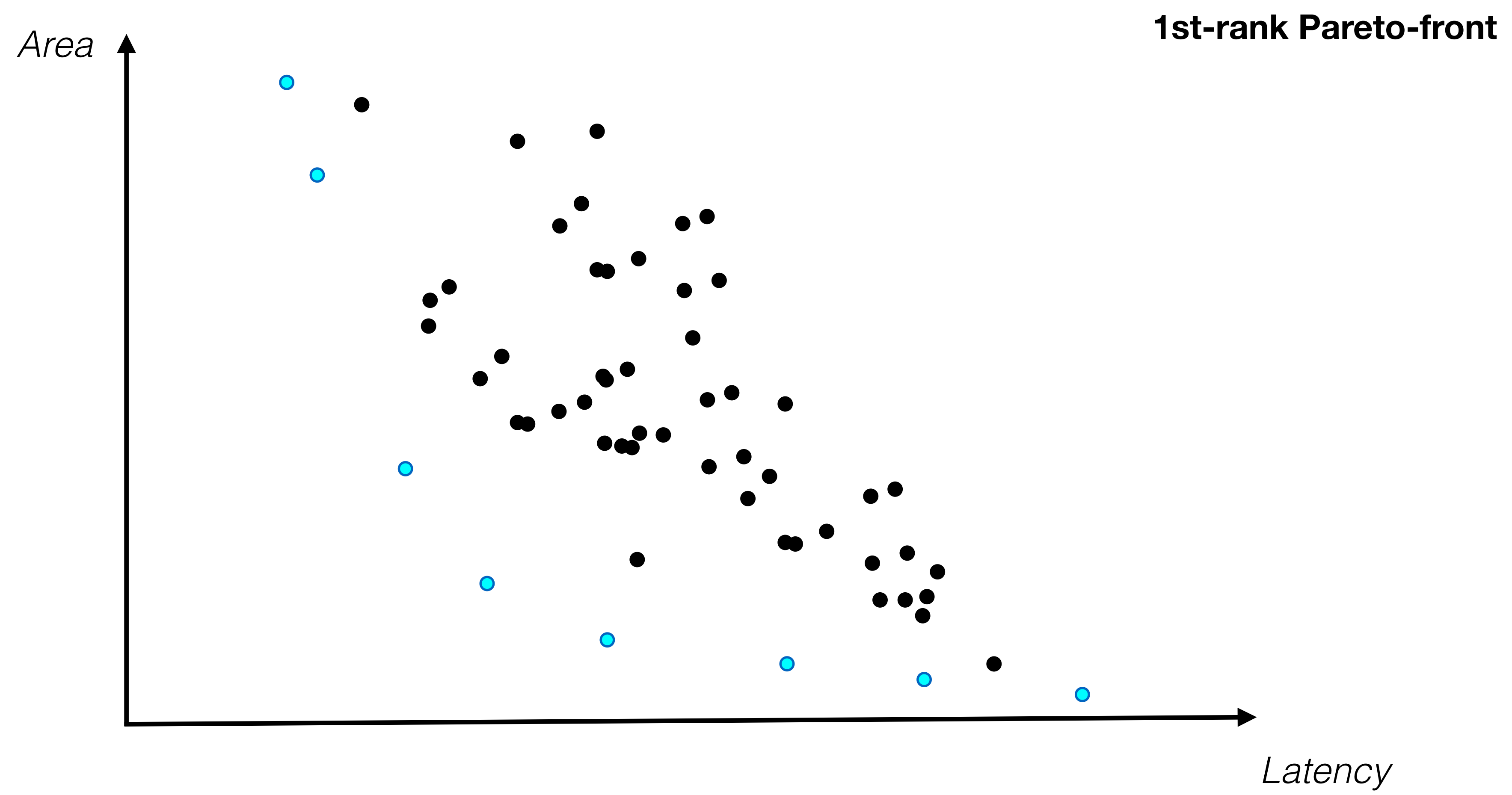


Domain		Inference						
Source knobs		K ₁ cyclic 256	K ₂ cyclic 8	K ₄ 32	K ₅ 64	K ₆ 10		
Target knobs	K ₁ <u>2P_BRAM</u>	K ₂ <u>2P_BRAM</u>	K ₃ <u>cyclic</u> , block 1, ..., 256, 512	K ₄ <u>cyclic</u> , block 1, ..., 8, ..., 128	K ₅ 1, ..., <u>32</u> , ..., 128	K ₆ 1, 2, 4, 8, <u>16</u>	K ₇ <u>10</u>	

Running Example

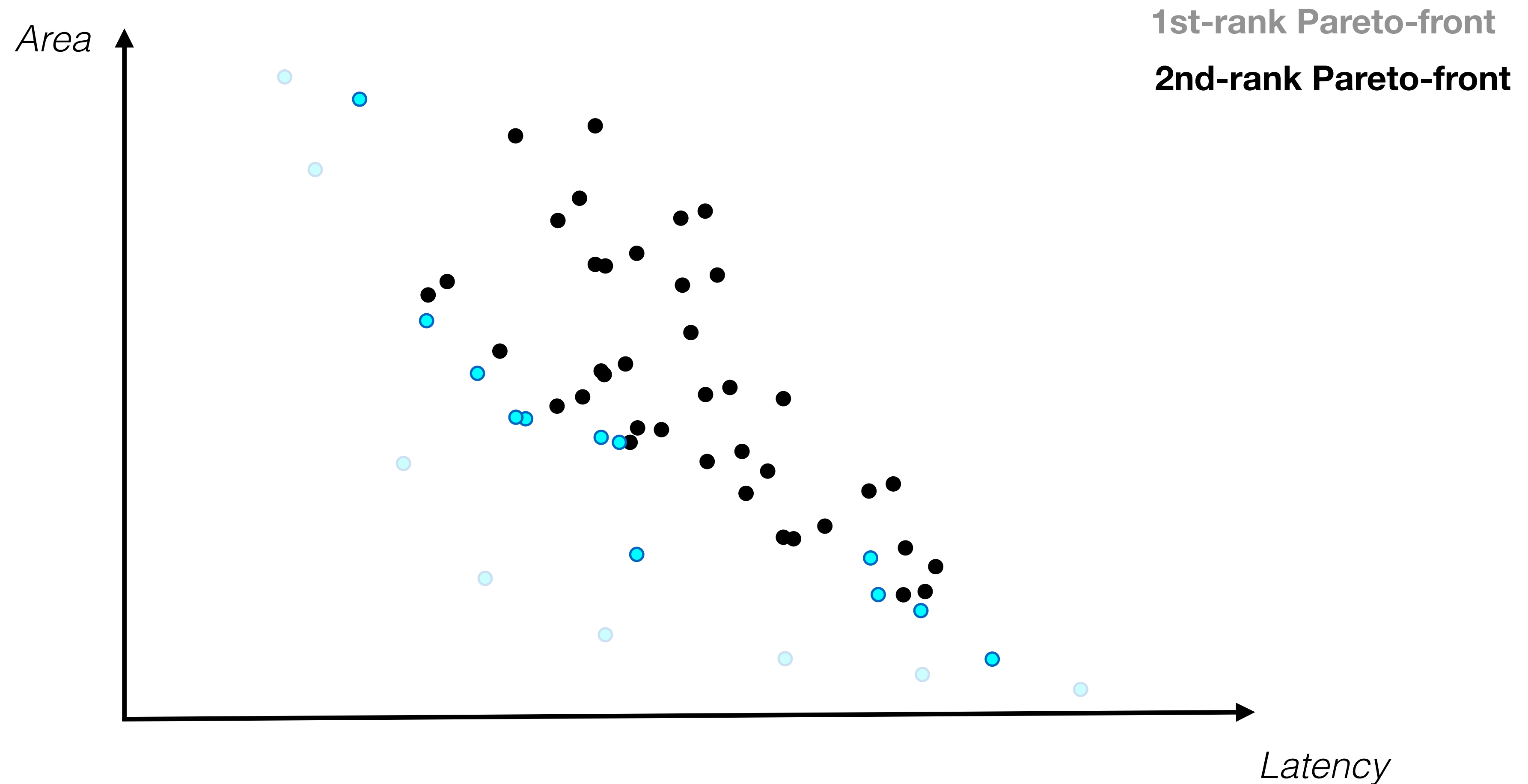
The methodology: Inference Process

The source design space is iteratively peeled and lower-rank Pareto frontiers are used for the inference.



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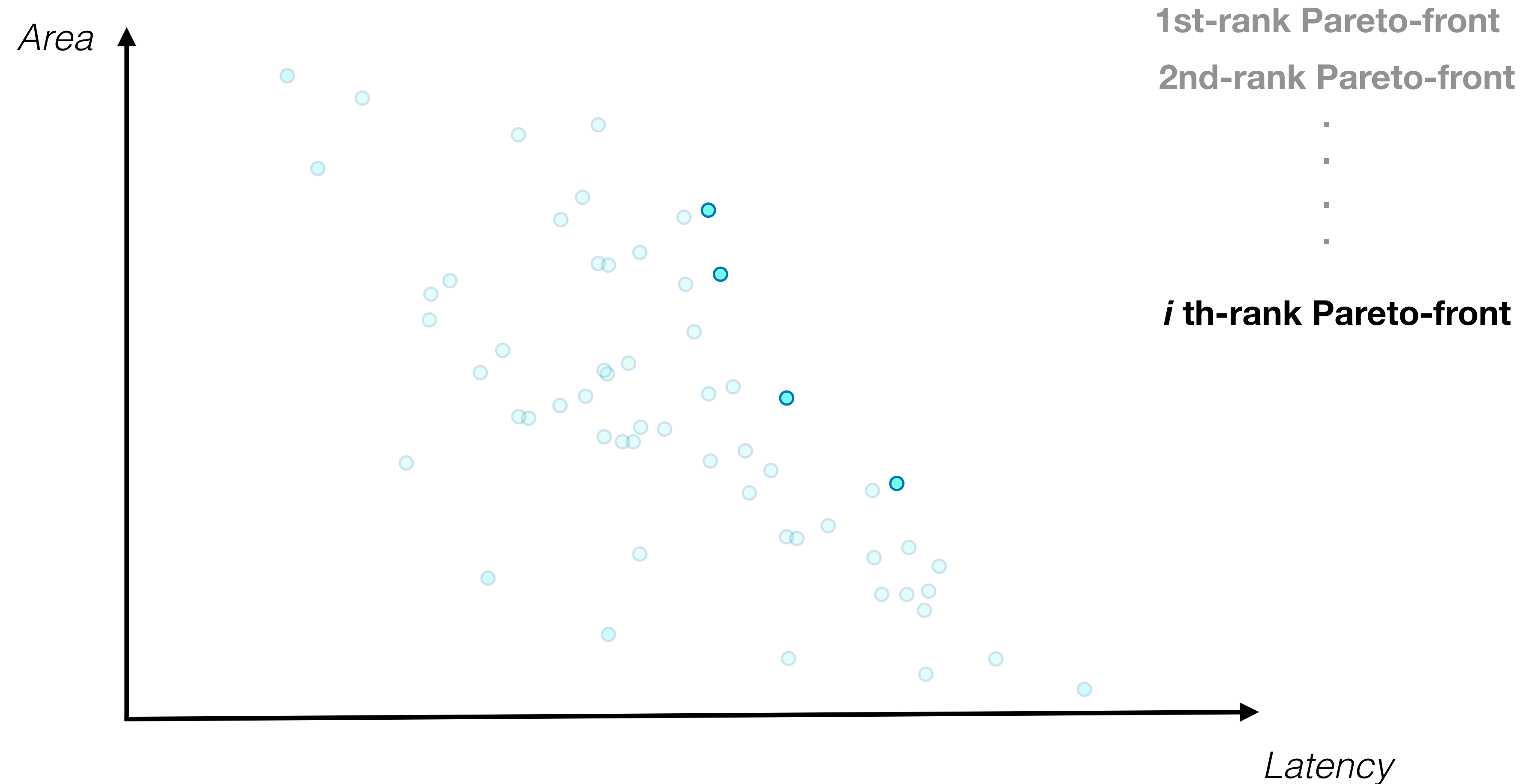


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Results

We have considered 39 out of 50 possible design from Machsuite[4].

For each of them we have performed an exhaustive exploration and used it as a ground-truth to evaluate the quality of the DSE.

We have used Average Distance from Reference Set (ADRS) metric to measure the distance among the retrieved Pareto frontier and the ground-truth.

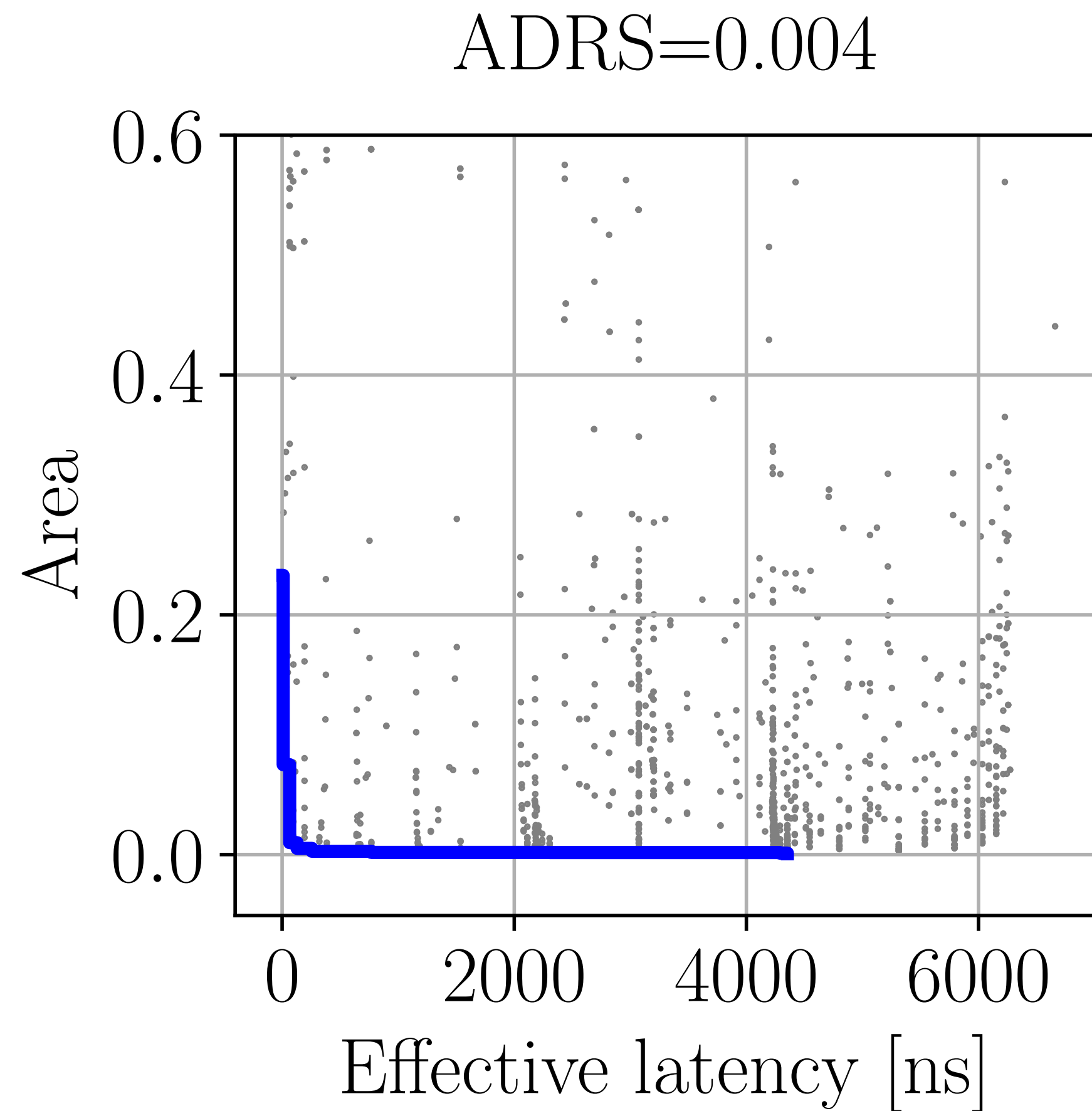
$$ADRS(\bar{P}, P) = \left[\frac{1}{|P|} \sum_{p \in P} \min_{\bar{p} \in \bar{P}} (d(\bar{p}, p)) \right]$$

$$d(\bar{p}, p) = \max \{ 0, (A_{\bar{p}} - A_p) / A_p, (L_{\bar{p}} - L_p) / L_p \}$$

[4] B. Reagen et al. International Symposium on Workload Characterisation, 2014.

Results

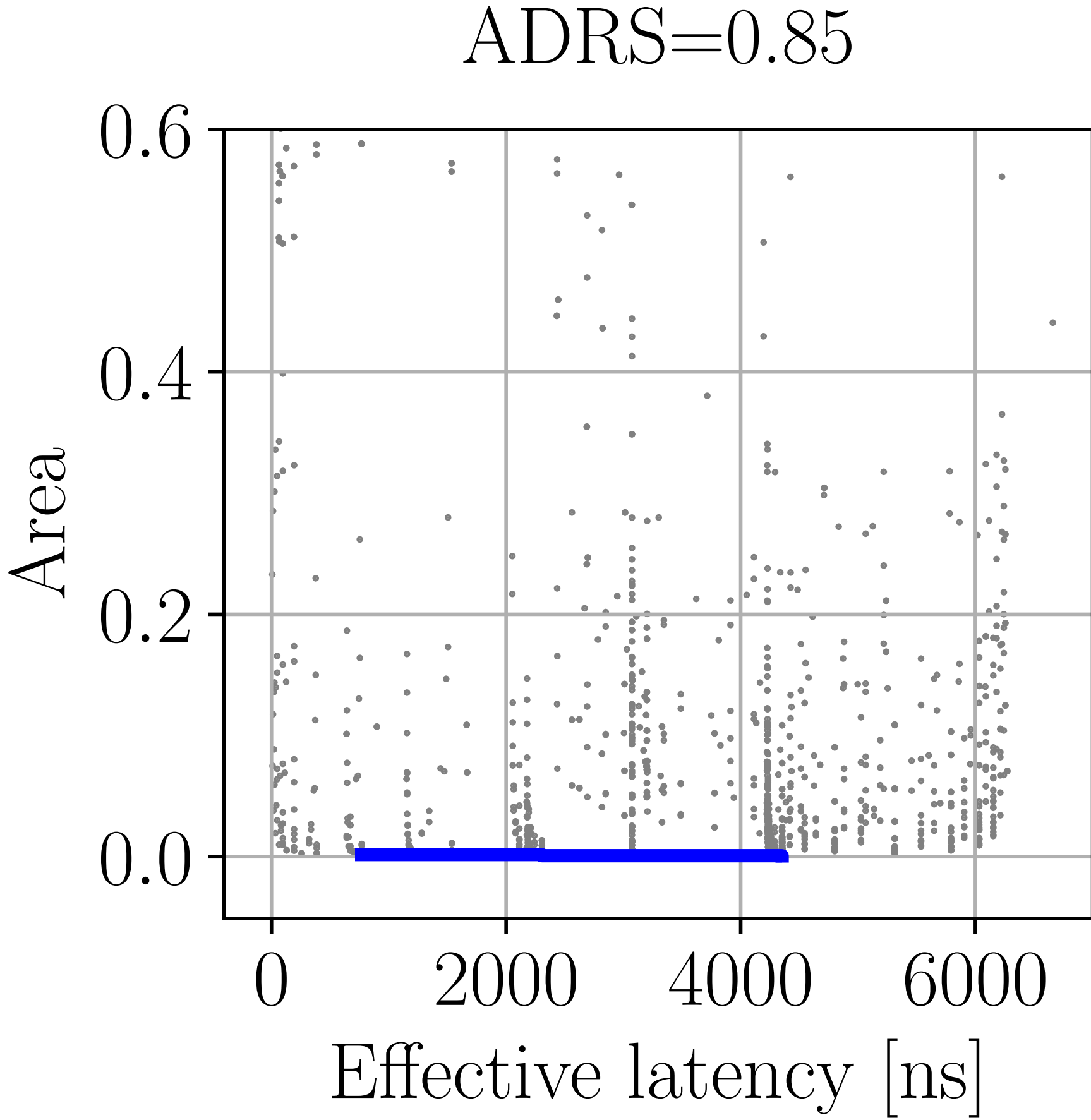
Effectiveness of the similarity metric: 1st-ranked source.



- ✓ High Specification Encoding similarity
- ✓ High Configuration Space Descriptor similarity

Results

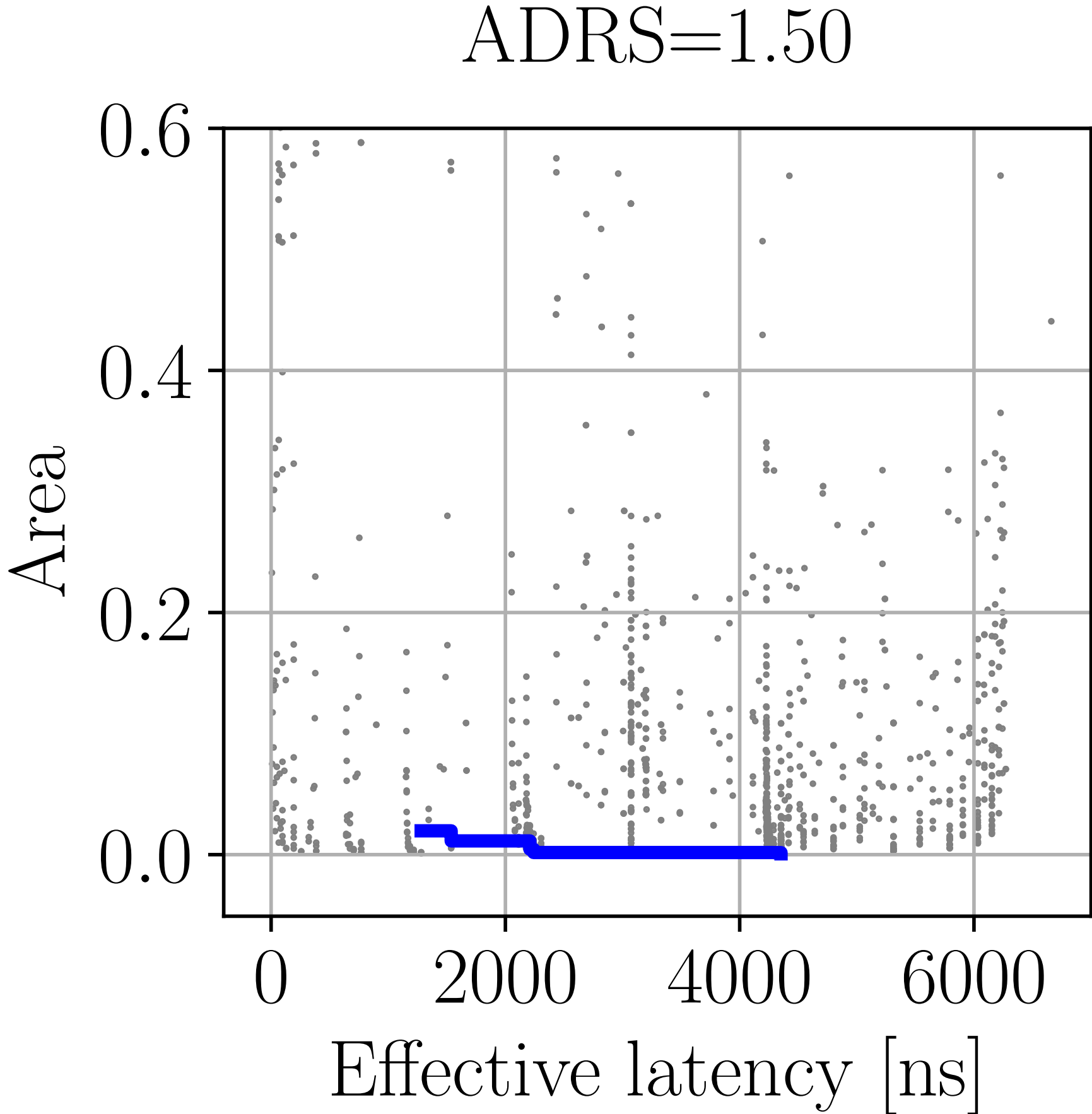
Effectiveness of the similarity metric: 30th-ranked source.



- X Low Specification Encoding similarity
- ✓ High Configuration Space Descriptor similarity

Results

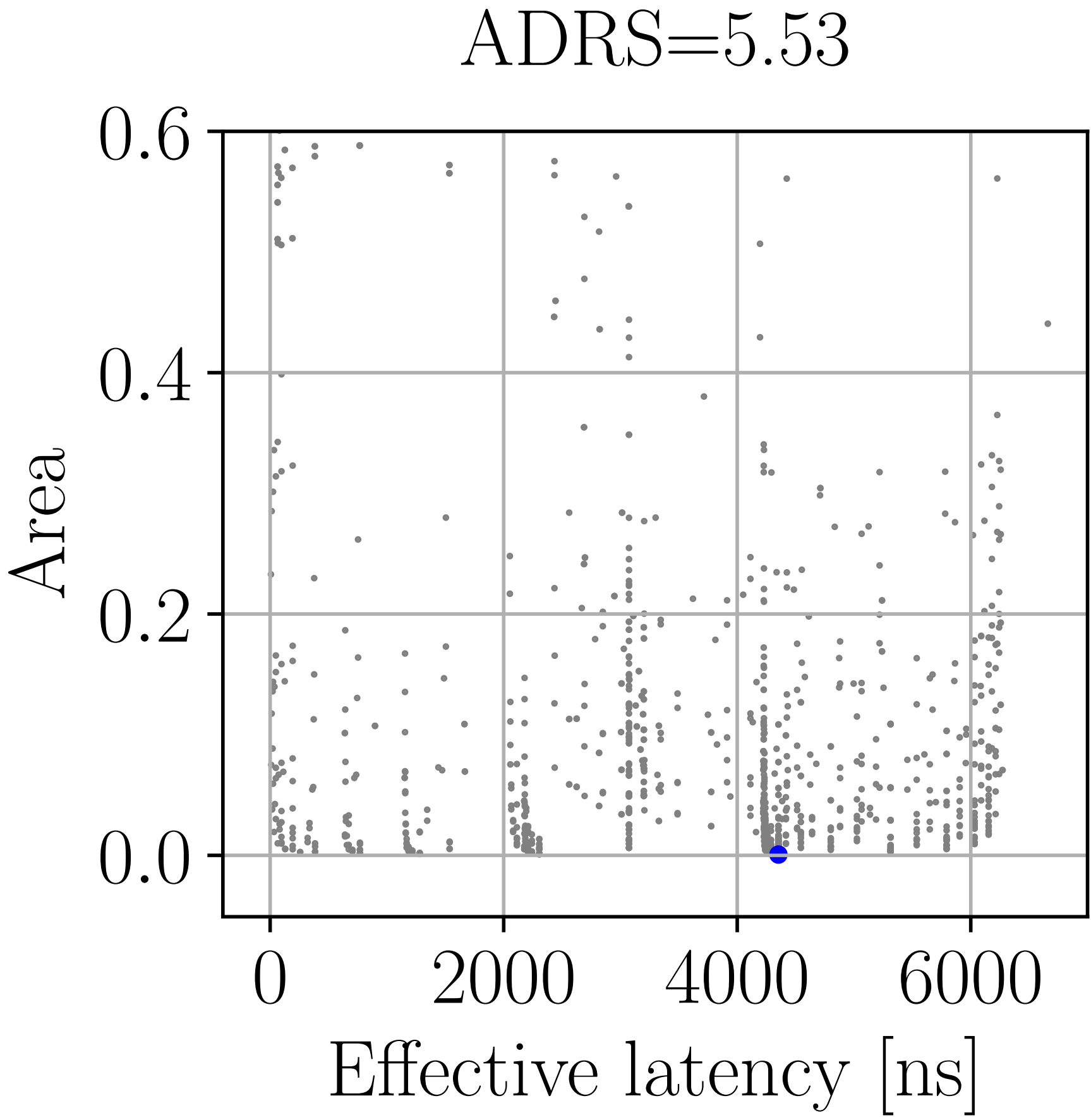
Effectiveness of the similarity metric: 35th-ranked source.



- ✓ High Specification Encoding similarity
- ✗ Low Configuration Space Descriptor similarity

Results

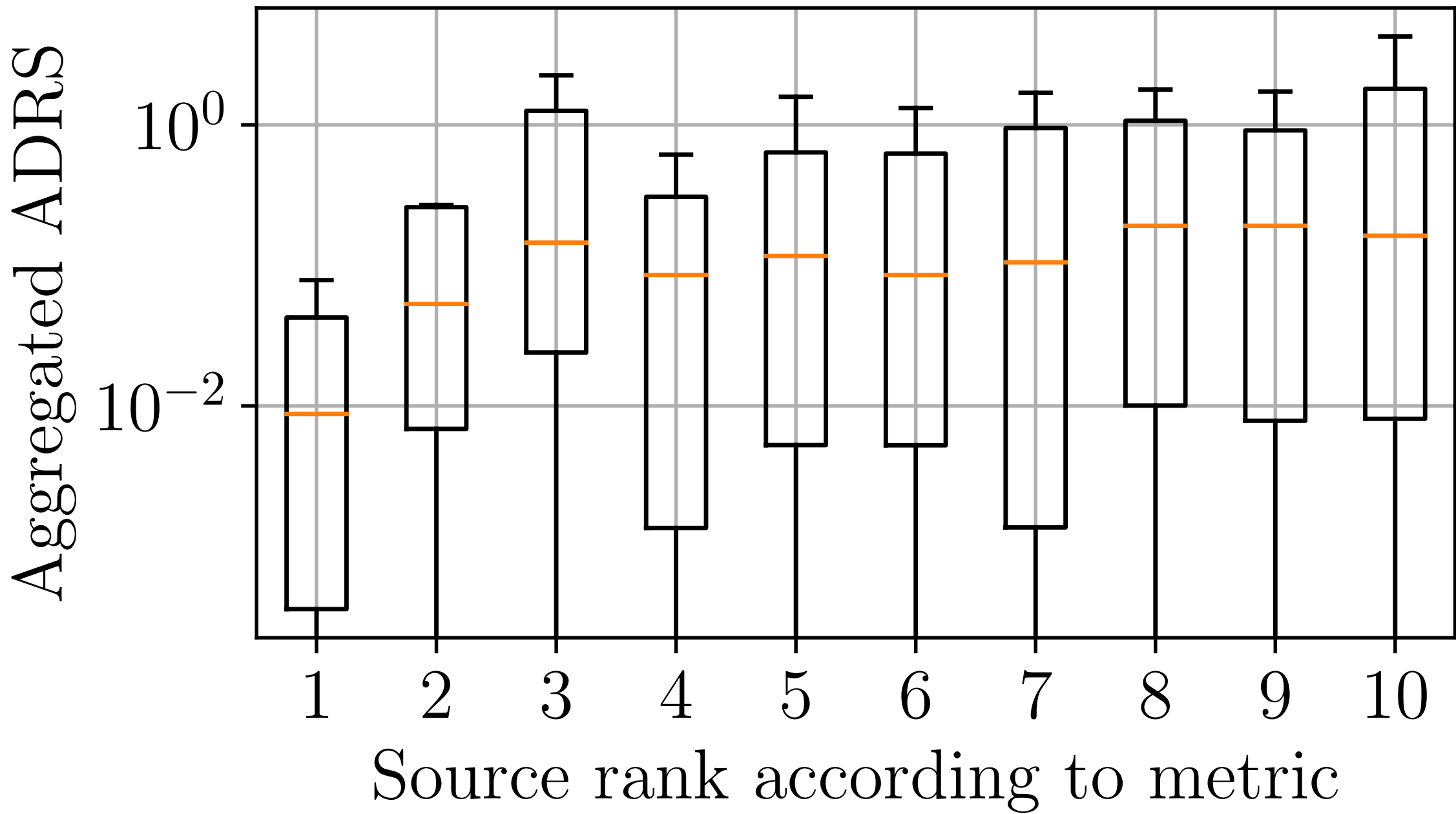
Effectiveness of the similarity metric: 37th-ranked source.



- X Low Specification Encoding similarity
- X Low Configuration Space Descriptor similarity

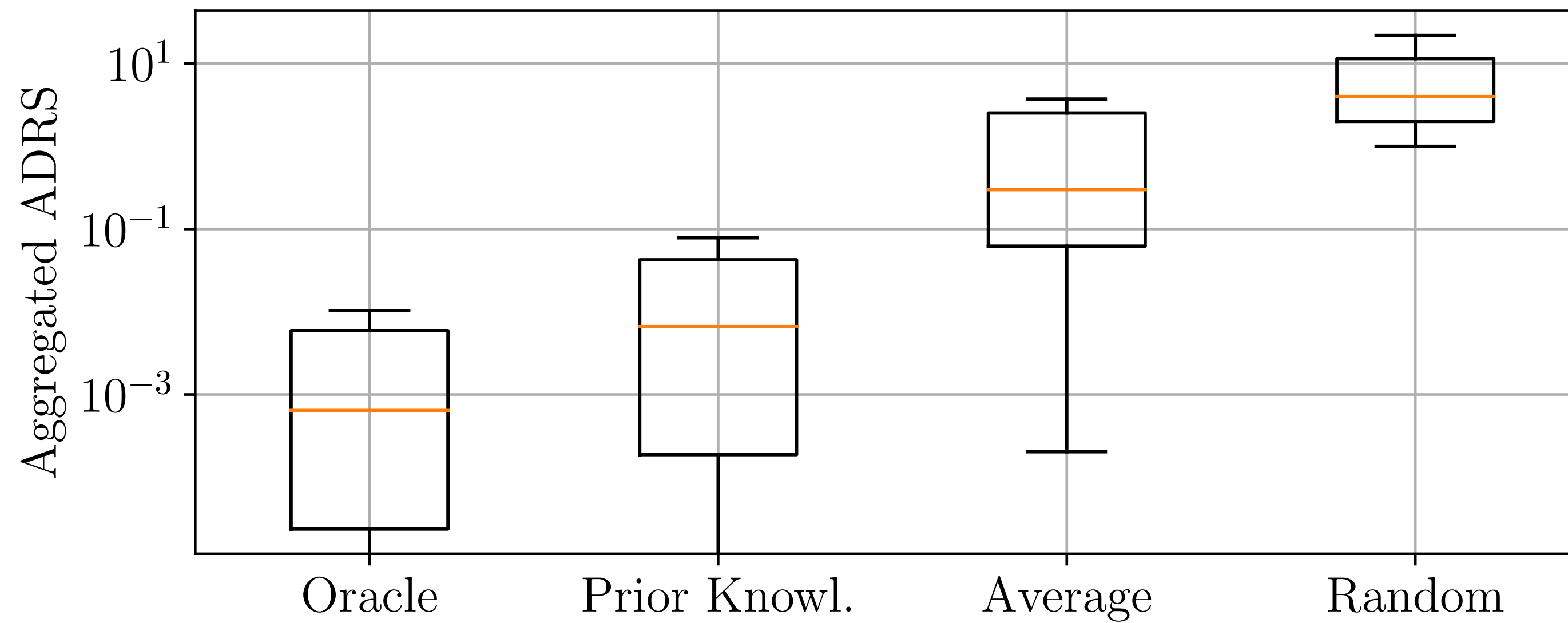
Results

Effectiveness of the similarity metric: source ranking.



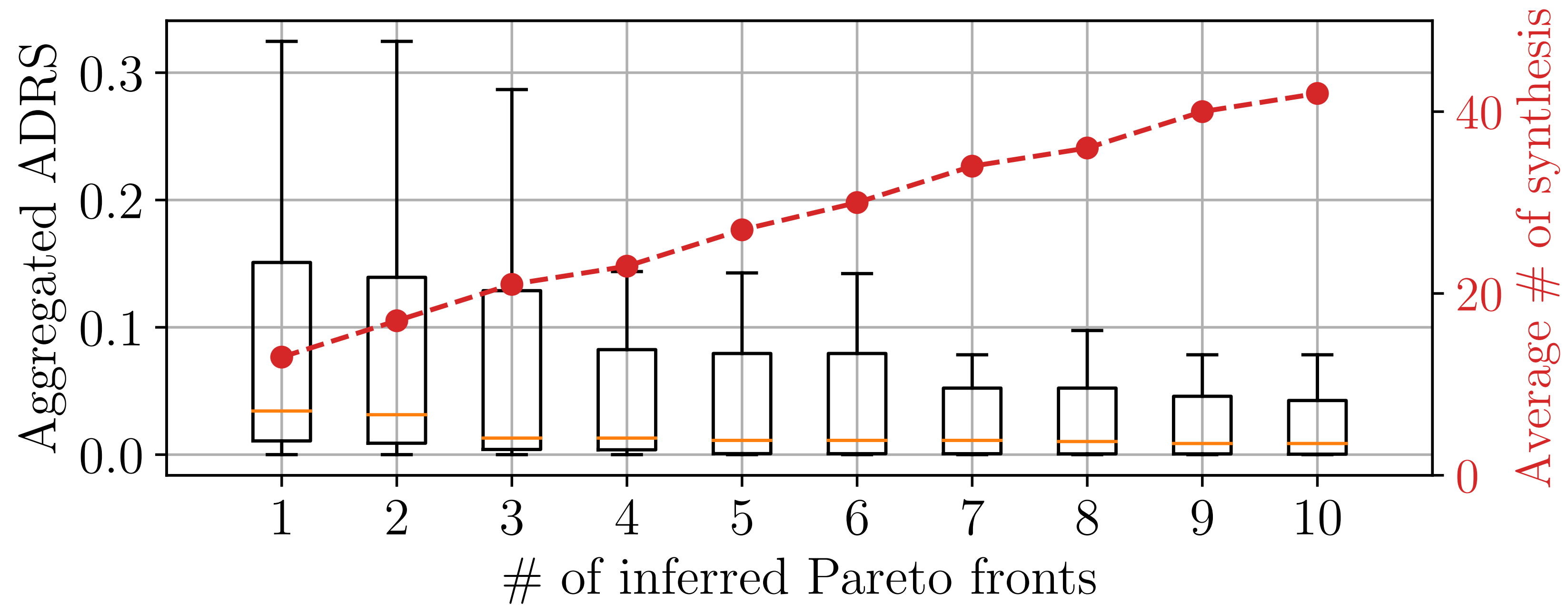
Results

Effectiveness of the similarity metric: selection criterion.



Results

Effectiveness of the similarity metric: influence of multiple Pareto frontier rank inference.



Results

Comparison of our methodology with respect to SoA ones for similar problems size.

CS	Prior Knowl.	Refinement-Based			Model-Based
		Lattice [10]	Cluster [9]	RF-TED [8]	Zhong [11]
< 200	7	36	37	155	NA
< 700	10	64	64	391	19
< 1800	22	230	290	1588	31
< 6000	19	460	460	1903	32
< 16000	NA	NA	NA	NA	35
< 32000	38	NA	NA	NA	NA

Number of synthesis required to reach an ADRS goal of 0.04.

- [8] H. Liu et al. Design Automation Conference, 2013.
- [9] L. Ferretti et al. IEEE Transactions on Emerging Topics in Computing, 2018.
- [10] L. Ferretti et al. International Conference on Computer Design, 2018.
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Database of DSEs will be
released soon!

Thank you for your attention!